Definitions and hypotheses

Statement of the main results

Sketch of the proof

Orbitally stable coupled standing waves for a coupled non-linear Klein–Gordon equation

Garrisi Daniele

Pohang Mathematics Institute, POSTECH

The 4th MSJ-SI Nonlinear dynamics in Partial Differential Equations Kyushu University, September 14, 2011

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● の Q @

Definitions and hypotheses

Statement of the main results

Sketch of the proof

The coupled non-linear Klein-Gordon equation

$$\begin{aligned} \partial_{tt} v_1 - \Delta_x v_1 + m_1^2 v_1 + \partial_{v_1} F(v) &= 0\\ \partial_{tt} v_2 - \Delta_x v_2 + m_2^2 v_2 + \partial_{v_2} F(v) &= 0 \end{aligned} \tag{CNLKG}$$

on F the following assumptions hold

- 1 $F\in C^1(\mathbb{R}^2,\mathbb{R})$ and F(0)=0;
- 2 $|DF(u)| \le c(|u|^{p-1} + |u|^{q-1})$ with 2 ;
- 3 $F(u_1, u_2) = -\beta |u_1 u_2|^{\gamma} + G(u), \ \beta > 0, \ 2 < 2\gamma < p;$

4
$$G \ge 0$$
, $G(u_1, u_2) = G(|u_1|, |u_2|)$

5
$$V(u) := m_1^2 u_1^2/2 + m_2^2 u_2^2/2 + F(u) \ge 0;$$

6 *G* is well-behaved with respect to the symmetric rearrangement

$$\int_{\mathbb{R}^N} G(u_1^*, u_2^*) \leq \int_{\mathbb{R}^N} G(u_1, u_2).$$

◆ロ > ◆母 > ◆臣 > ◆臣 > ○ ● ● ●

Definitions and hypotheses

Statement of the main results

Sketch of the proof

In |

We are looking for standing-wave pairs solutions to (CNLKG).

$$\begin{aligned} v_j(t,x) &= u_j(x)e^{-i\omega_j t}, \quad 1 \le j \le 2\\ \text{particular, a solution } (u,\omega) \in H^1(\mathbb{R}^N,\mathbb{R}^2) \times \mathbb{R}^2\\ &-\Delta u_1 + (m_1^2 - \omega_1^2)u_1 + \partial_{v_1}F(u) = 0\\ &-\Delta u_2 + (m_2^2 - \omega_2^2)u_2 + \partial_{v_2}F(u) = 0\\ &u_j > 0 \end{aligned}$$

Definitions and hypotheses

Statement of the main results

Sketch of the proof

for

Furthermore, (u, ω) has the following variational characterisation

$$E(u,\omega) = \inf_{M_c} E =: I(c)$$

some
$$c \in \mathbb{R}^2$$
 with $c_j > 0$.
 $E \colon H^1(\mathbb{R}^N, \mathbb{R}^2) \times \mathbb{R}^2 \to \mathbb{R}$
 $(v, \alpha) \mapsto \frac{1}{2} \sum_{j=1}^2 \|Dv_j\|^2 + m_j^2 \|v_j\|^2 + \int_{\mathbb{R}^N} F(v)$

$$C_j \colon H^1(\mathbb{R}^N, \mathbb{R}^2) \times \mathbb{R}^2 \to \mathbb{R}$$
$$(v, \alpha) \mapsto \alpha_j \|v_j\|^2, \quad 1 \le j \le 2$$

$$M_{c} = \{(v, \alpha) \mid C_{j}(v, \alpha) = c_{j}\}.$$

▲ロト ▲母 ▶ ▲ 臣 ▶ ▲ 臣 ▶ ● 臣 ● のへぐ

Definitions and hypotheses

G

Given
$$(\phi, \phi_t) \in H^1(\mathbb{R}^N, \mathbb{C}^2) \oplus L^2(\mathbb{R}^N, \mathbb{C}^2) =: X$$
 there exists $T > 0$ and a unique

$$v\in C_tH^1_x(0,\,T;\mathbb{R}^N)\cap C^1_tL^2_x(0,\,T;\mathbb{R}^N)$$

such that v solves (CNLKG) and

$$v(0) = \phi, \quad v'(0) = \phi_t.$$

In the scalar case the problem was addressed by J. Ginibre and G. Velo (Math. Zeit., 1985).

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ◆ ○ ○ ○

Definitions and hypotheses

Statement of the main results

Sketch of the proof

From the assumption

$$F(u_1, u_2) = F(|u_1|, |u_2|)$$

we have conserved quantities

$$\begin{aligned} \mathbf{E} \colon X \to \mathbb{R}, \qquad & (\text{Energy}) \\ (\phi, \phi_t) \mapsto \frac{1}{2} \int_{\mathbb{R}^N} |\phi_t|^2 + |D\phi|^2 \\ &+ m_1^2 |\phi_1|^2 + m_2^2 |\phi_2|^2 + 2F(\phi) \end{aligned}$$
$$\begin{aligned} \mathbf{C}_j \colon X \to \mathbb{R}, \quad 1 \le j \le 2 \\ (\phi, \phi_t) \mapsto -\text{Im} \int_{\mathbb{R}^N} \phi_t^j \overline{\phi_j}. \end{aligned} \qquad (\text{Charges})$$

If $(\phi, \phi_t) = (u_1, u_2, -i\omega_1 u_1, -i\omega_2 u_2)$, then **E** and **C**_j correspond to $E(u, \omega)$ and $C_j(u, \omega)$.

Definitions and hypotheses

Statement of the main results

Sketch of the proof

Orbital Stability

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● の Q @

A subset $S \subset X$ is said stable if for every $\varepsilon > 0$ there exists $\delta > 0$ such that, if

 $\operatorname{dist}(p,S) < \delta$

then the local solution v of (CNLKG) with initial datum p is defined on $[0,+\infty)$ and

$$\operatorname{dist}((v(t),v'(t)),S)$$

An initial datum $q \in X$ is said orbitally stable if there exists a closed, finite-dimensional manifold S such that

1 S is positively invariant;

2 S is stable.

Definitions and hypotheses

Statement of the main results

Sketch of the proof We say that the standing-waves pair solution to (CNLKG)

$$(u_1, u_2, -i\omega_1u_1, -i\omega_2u_2)$$

is orbitally stable if

$$\Gamma(u,\omega) = \begin{cases} \left(\lambda_1 u_1(\cdot+y), \lambda_2 u_2(\cdot+y), \\ (-i\lambda_1\omega_1 u_1(\cdot+y)), -i\lambda_2\omega_2 u_2(\cdot+y))\right) \\ (\lambda,y) \in S^1 \times S^1 \times \mathbb{R}^N. \end{cases}$$

is stable. Given $c \in \mathbb{R}^2$, we define

$$\Gamma_c := \bigcup_{E(u,\omega)=I(c)\ (u,\omega)\in M_c} \Gamma(u,\omega)$$

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● の Q @

called *ground state* (V. Benci, J. Bellazzini *et al.*, Adv. Nonlinear Stud., 2010).

Definitions and hypotheses

Statement of the main results

Sketch of the proof J. Shatah 1983 (Comm., Math, Physics, 1983) NLKG, least energy solutions; orbital stability in $H_r^1(\mathbb{R}^N)$, $N \ge 3$ with $F(u) = -|u|^{p-1}u$ and p < 1 + 4/N. Stable for $\omega \in (\omega^*, 1)$;

J. Bellazzini, V. Benci, C. Bonanno, M. Micheletti (Adv. Nonlinear Stud., 2010) NLKG, $E(u, \omega) = \inf_{M_c} E$; stability of the ground state and $\Gamma(u, \omega)$ (under a non-degeneracy assumption); scalar case and $N \ge 3$;

J. Zhang, Z. Gan, B. Guo 2010 (Acta Math. Appl. Sin. Engl. Ser., 2010) CNLKG; analogous results to the Shatah's work, $F(u_1, u_2) = -|u_1|^{p+1}|u_2|^{q+1}$, $\omega_1 = \omega_2 \in (\omega^*, 1)$.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Definitions and hypotheses

Statement of the main results

Sketch of the proof

Theorem

- **1** For every c such that $c_j > 0$ the ground state is stable;
- 2 for every (u,ω) such that $E(u,\omega)=I(c)$ and there exists $r_0>0$ such that

$$\mathsf{\Gamma}(\mathsf{v},\alpha)\neq\mathsf{\Gamma}(\mathsf{u},\omega)\Rightarrow\mathsf{B}(\mathsf{\Gamma}(\mathsf{u},\omega),\mathsf{r_0})\cap\mathsf{\Gamma}(\mathsf{v},\alpha)=\emptyset$$

 $\Gamma(u,\omega)$ is stable (i.e. the corresponding standing-wave is orbitally stable).

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● の Q @

Definitions and hypotheses

Statement of the main results

Sketch of the proof The proof is carried out by contradiction: let $(\Phi_n) \subset X \ \delta > 0$ and $(t_n) \subset \mathbb{R}$ be such that

$$\operatorname{dist}(\Phi_n,\Gamma_c)\to 0, \quad \operatorname{dist}((v_n(t_n),v_n'(t_n)),\Gamma_c)\geq \delta.$$

We know that

 $\mathbf{E}((v_n(t_n),v_n'(t_n)) \rightarrow I(c), \quad \mathbf{C}_j((v_n(t_n),v_n'(t_n)) \rightarrow c_j.$

Theorem

Let $(\Psi_n) \subset X$ be a sequence such that

$$\mathsf{E}(\Psi_n) \to I(c), \quad \mathsf{C}_j(\Psi_n) \to c_j.$$

Then

$$\operatorname{dist}(\Psi_n, \Gamma_c) \to 0.$$

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● の Q @

See also J. Bellazzini, V. Benci *et al.* (Adv. Nonlinear Stud., 2010).

Definitions and hypotheses

Statement of the main results

Sketch of the proof

Theorem

Given a minimising sequence (u_n, ω_n) of E on M_c , then

$$u_{n_k} = u(\cdot + y_k) + o(1) \text{ in } H^1(\mathbb{R}^N, \mathbb{R}^2), \quad \omega_{n_k} \to \omega$$

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● の Q @

for some (u, ω) such that $E(u, \omega) = I(c)$ and $(y_k) \subset \mathbb{R}^N$.

Definitions and hypotheses

Statement of the main results

Sketch of the proof In turn, the preceding Theorem follows from:

1 the Lemma I.1 of P.L. Lions (Ann. Inst. H. Poincaré Anal. Non Linéaire 1, 1984, no. 2). The term

 $-\beta |u_1 u_2|^{\gamma}$

rules out the vanishing case;

2 given c, c', there exists $\varepsilon > 0$ and $d = d(\sigma, \tau) \in (0, 1)$ given non-negative radially symmetric

 $((u,\omega),(u',\omega'))\in M_c\times M_{c'}$

with compact and disjoint support

 $E(u,\omega) \leq I(c) + \varepsilon, \quad E(u',\omega') \leq I(c') + \varepsilon.$ $\|D(u+u')^*\|^2 \leq c(\|Du\|^2 + \|Du'\|^2)$ $(3) E(u_n - u,\omega) = E(u_n,\omega) - E(u,\omega) + o(1) \text{ if } u_n \rightharpoonup u.$

◆ロ > ◆母 > ◆臣 > ◆臣 > ○ ● ● ●

Definitions and hypotheses

Statement of the main results

Sketch of the proof



Definitions and hypotheses

Statement of the main results

Sketch of the proof

The non-degeneracy condition

It is interesting to know whether the non-degeneracy condition can be dropped from our assumption.

- it is possible to drop the non-degeneracy requirement to obtain the orbital stability of Γ(u, ω);
- 2 or, are there solutions to a NLKG which connect points arbitrarily close to $\Gamma(u, \omega)$ to points close to $\Gamma(v, \alpha)$?

Definitions and hypotheses

Statement of the main results

Sketch of the proof

Acknowledgements

- Professor Vieri Benci and Professor Jaeyoung Byeon for their helpful suggestion;
- this work was supported by the Priority Research Centers Program through the National Research Foundation of Korea (NRF) funded by the Ministry of Education, Science and Technology (Grant #2009-0094068);
- thank you for your attention.